C1509

PANCAKE - CONDUCTIVE POLYMER
PRECISION POTENTIOMETER

Conductive Polymer

PRESENTATION

The rotary potentiometer **C1509** is provided with a bearingless design. This pancake interface, combined with its small size, make the **C1509** particularly adapted to applications such as micro-robotics, avionics or measurement devices.

This model offers a wide range of options: mechanical interface, connections, precision, effective electrical travel...

High Performances

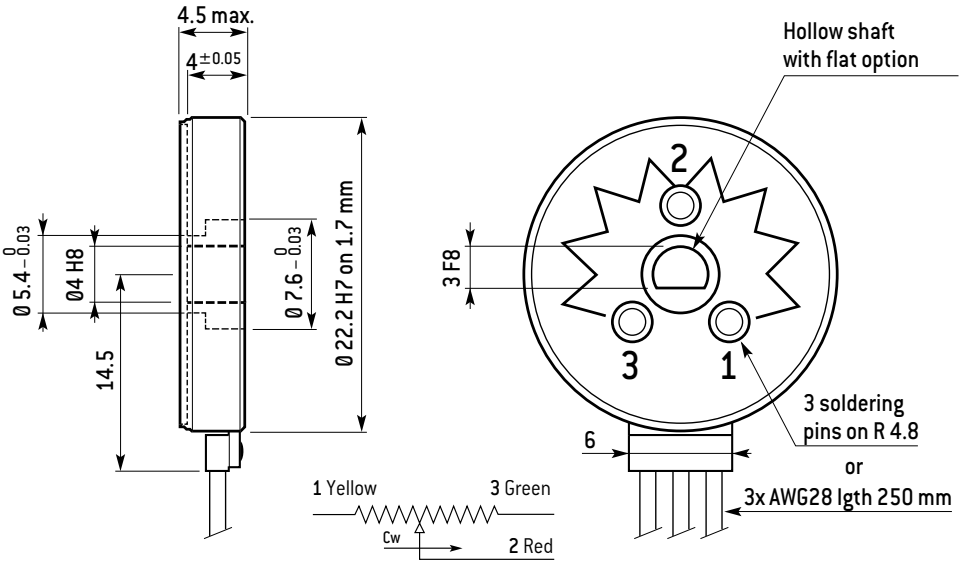
Low profile

ENVIRONMENTAL DATA	
Operating temperature	–55°C to +70°C
Storage temperature	–45°C to +80°C
Vibrations (sine 3 axis, 1.5 mm, 10 @ 2 kHz)	20g
Shocks (1/2 sine, 3 axis, 11 ms)	50 g

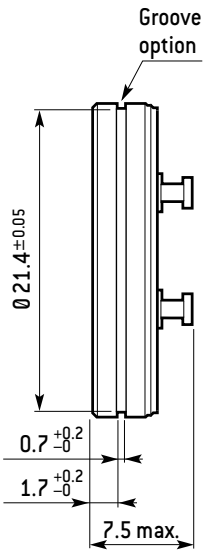
MATERIALS	
Body and shaft	aluminum alloy + anodic oxydation
Bearing	Bearingless (pancake type sensor)

DIMENSIONS (in mm)

Radial wires outlet option



Soldering pin option



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STANDARD ELECTRICAL DATA	
Nominal resistance	5.1 kΩ
Resistance tolerance (Rn) at 20°C	± 10 %
Independent linearity	±0.5 %
Output smoothness	≤ 0.05%
Insulation resistance (500 V_{DC})	> 1 GΩ
Whistand voltage	500 V_{AC} 50 Hz 1 mn
Backlash with 5 V *	≤ 4mv (0.048°) **
Rated dissipation at 70°C	1 W
Wiper current	1 mA max.

* If mounting conditions are respected and not including the mechanical play on the customer installation.
** Tested according to MIL-PRF-39023 except

MECHANICAL CHARACTERISTICS	
Effective electrical travel (EET)	Up to 60°
Mechanical travel (MT)	360°
Starting torque	≤ 0.1 N.cm **
Axial mounting load	5 N max.

** Tested according to MIL-PRF-39023 except

HOW TO ORDER

	Nominal resistance (in code)	Linearity in code (±%)	Electrical travel (°)	Option* in code	RoHS compliance
C1509	•••	•	•••	••	•
	470	Z	020	00	W
	to	to	to	01	N
	10M	F	340	02	
				...	
	470: 470 Ω **1K0**: 1 000 Ω **4K7**: 4 700 Ω **10M**: 10 MΩ etc.	**Z**: ±0.025% **A**: ±0.05% **B**: ±0.1% **C**: ±0.25% **D**: ±0.5% **F**: ±1%	**020**: 20° **340**: 340° etc.	**00**: No option **01**: Option 1 **02**: Option 2 etc.	**W**: RoHS compliant **N**: Non compliant

* For options, please contact us.

Potentiometers General information

1. INTRODUCING EXXELIA GROUP POTENTIOMETERS

For over 50 years, **EXXELIA GROUP** has been developing potentiometric sensors for civil and spatial applications and for the defense sector. **EXXELIA GROUP** has special know-how in the two basic manufacturing techniques used to produce potentiometer sensor tracks:

- **Conductive film technology**
- **Wirewound technology**

Apart from the different technologies used, these potentiometers break down into several families:

- rotary potentiometers (for copying positions or driving rotary systems),
- single-turn or multi-turn potentiometers
- pancake potentiometers (monobloc with a mobile "wiper" part inseparable from the shaft and no ball bearings),
- Linear motion potentiometers (for copying positions or driving systems with linear translation motion),
- digital potentiometers (equipped with an analog-digital converter –> 16 bits),
- rotary switches providing discrete signals on multiple bits and used for example to define angular sectors (used to set limits for security sectors when mounted on weapon station Slip rings).

Summary definitions of terms related to non-wirewound (conductive polymer) precision potentiometers as per standard **NF C 93255** and **MIL R 39023** and to wirewound potentiometers as per standard **NF C 93265** and **MIL R 12934**:

Nominal resistance (Rn): rated label value of the potentiometer.

Total resistance (Rt): value measured between the input and output, Rt should be between the Rn + and the Rn – tolerances.

Effective electrical travel: value in degrees of angular deviation corresponding to an effective variation in resistance. See fig. 1, which also shows total electrical travel and mechanical travel Two possibilities are presented: fig. 1A for continuous rotation single turn potentiometers and fig. 1B for single or multi-turn potentiometers with stops.

Standardized definitions for mechanical travel and electrical travel:

Fig. 1A - Single or multi-turn potentiometer with stops.

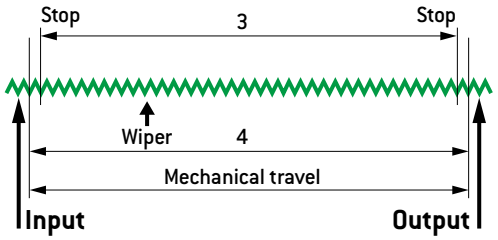
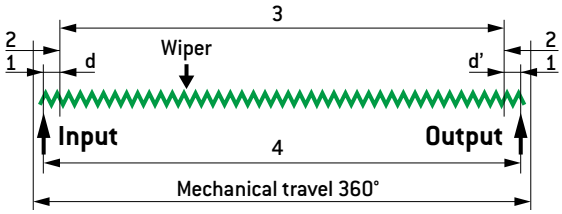


Fig. 1B - Single-turn continuous rotation potentiometer.



1. dead space (electrical discontinuity)

2. non-conformity space (difference between the 360° mechanical travel and the actual electrical travel, fig. 1A

3. effective electrical travel (value corresponding to an effective variation in resistance in which conformity is verified)

4. total electrical travel (in the example in fig. 1B the total electrical travel, or mechanical travel, may be taken for the effective electrical travel)

dd' - overtravel (as in fig. 1A)

- single turn potentiometer: mechanical travel at less than 360°
- n-turns potentiometer mechanical travel greater than n, 360°

Movement: a movement includes the clockwise and counterclockwise travels of the shaft

Backlash: value in degrees of the angle of rotation that does not result in any contact travel during a change in direction

Function: the relationship between the electrical value to be obtained (theoretical function) or obtained (actual function) at the output terminals and the wiper position in the actual electrical travel

Conformity deviation: positive or negative deviation in the values of the functions desired and obtained for each wiper position linearity deviation for linearity function

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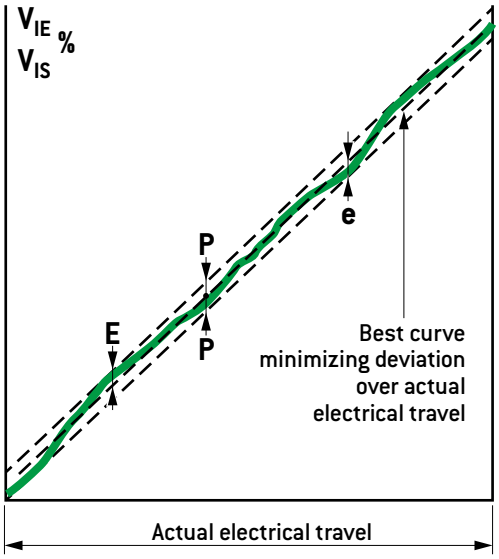
Conformity: percentage between the maximum conformity deviation (absolute value) and the maximum electrical value measured between input and output, as in fig. 1A and 1B. linearity, for linearity function.

Corrected deviation: absolute value of the deviation between the best curve of the effective electrical travel minimizing the deviations and the curve representing the desired function.

Fig. 2 - Independent linearity curve



V_{IE} Voltage between input and wiper
V_{IS} Voltage applied to potentiometer terminals
E Upper deviation
e Lower deviation
P Conformity tolerance $\frac{E+e}{2} < P$
– – Authorized deviations

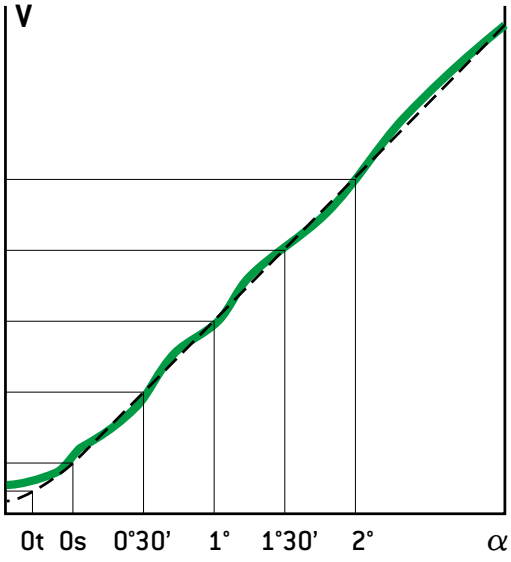
Independent conformity: percentage between the absolute value of the maximum corrected deviation and the maximum electrical value measured between input and output Independent linearity for the linearity function.

Theoretical angular resolution: rotation angle formed by the wiper passing from one turn to the next. For a linear variation law it is the quotient of the total electrical travel over the number of turn. For a non-linear variation law the angle may vary in function of the wiper position. For the conductive polymer technology, the resolution is consider as "infinite".

Equivalent noise resistance (wirewound potentiometers): quotient of the maximum peak voltage (read on an oscilloscope as specified in standards) measured at the output during wiper travel, and the constant DC voltage at the wiper.

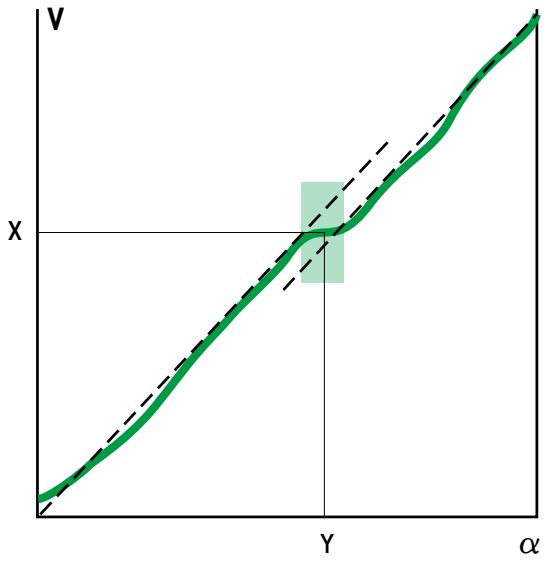
Output smoothness (nonwirewound potentiometers): ratio expressed in percentage of the greatest variation between the output voltage (measured as specified by the standards) and the applied voltage on the input.

Fig. 3 - Plastic Film potentiometer



– – Theoretical curve
Actual curve
0t Theoretical zero
0s Assumed zero

Fig. 4 - Voltage tap effects



– – Theoretical curve
Actual curve
Voltage tap effects zone
X Tap value
Y Tap position

Potentiometers General information

EXXELIA GROUP standard production precision potentiometers are manufactured using the technology wirewound or conductive polymer (norm/virewound).

Conformity to standards is given for each type, but performance after endurance tests is always superior to the even most stringent specifications presently applicable.

The Following specific characteristics of each technology are proceeded, when applicable by one of the followings sign:

NOTE	CHARACTERISTIC
++	Extremely favourable characteristic
+	Favourable characteristic
	Normal characteristic
–	Less favourable characteristic

2. WIREWOUND TECHNOLOGY

The main characteristics of this standard technology are as follows:

+ Low resistance:

The Wirewound technique enables the production of components with low ohmic values (from 100 ohms).

Independent conformity:

In general for the linear function, the independent linearity is maintained when requested, at a value within a range linked to the geometric parameters of the potentiometer (between ±0.5% and 2% for size 05, between ±0.05% and 0.5% for sizes 20 or 30 for single turn potentiometers; between ±0.01% and ±0.25% for multi-turn potentiometers).

++ Contact resistance:

Very low. The metal to metal contact resistance is situated at a value of approximately 200 milliohms.

+ Output current:

Since the contact resistance is very low, the current travelling through the wiper is in large part determined by the wire diameter (lower as the resistance of the potentiometer is higher) and by the size of the potentiometer (10-30mA for a 10 000 ohms potentiometer from size 05 to size 30).

– Theoretical angular resolution:

The turns/degrees ratio indicates output voltage variation by values which are increasingly discrete as the number of turns increases, Resistance is thus higher (0.6 to 1.5 turns/degrees from size 05 to size 18 for a resistance of 100 ohms, 2.3 to 8.5 turns/degrees from size 05 to size 30 for a resistance of 10 kohms; most favorable cases where no turn is “bypassed”).

– Equivalent noise resistance:

Voltage variations which appear during wiper travel from one turn to the next enable determination of the equivalent noise resistance (value set by standard at less than or equal to 25 ohms, may be decreased, for example, to less than or equal to 1 ohm for a 10 kohm potentiometer, size 18).

+ Temperature coefficient:

The potentiometer temperature coefficient strictly speaking is directly a function of the temperature coefficient of the wire used (less than or equal to 20 ppm/°C for average values).

– Performance versus frequency:

The input and output impedances depend on several parameters: coil length, wiper position, resistance value and type of case. The frequency range is limited (quadrature voltage: 0.1% for Rn 1 kohm, With F= 1 kHz, 2% for Rn 100 kohm, with F = 200 Hz).

Life:

The abrasion of the wire produced by the friction between the wiper and the coil has a detrimental effect on the linearity and increases the resistance value, particularly in the frequent case of travel limited to a small portion of the coil (specifications indicated for each type, average endurance at 40 rpm: 10^5 shaft revolutions or 5.10^5 movements). A life exceeding 1.10^7 shaft revolutions may be obtained in certain specific cases. Specific studies upupon request.

Potentiometers General information

3. CONDUCTIVE POLYMER TECHNOLOGY (NON-WIREWOUND)

The principal characteristics of this technology are summarized below.

+ Absolute conformity:

The conformity range linked to the geometric parameters of the potentiometer is more or less comparable to that of Wirewound potentiometers. However, the travel correction principle enables obtention of much superior precision.

– Contact resistance:

Higher than that of a wirewound potentiometer, it varies from tens to several hundred ohms (for example, 80 ohms for a 10 kohm size 18 potentiometer).

– Output current value:

To avoid heating by Joule effect at the contacts and resulting microdestruction of the conductive polymer path, the current flowing through the wiper, or output current, must be limited (milliampere value).

+ Almost infinite resolution:

Because of the perfectly polished nature of the surface of the conductor material with which the conductive polymer is doped (granulation measured in angstroms 1 Å - 10^{-10} m), resolution is practically infinite.

++ Output smoothness:

Linked to the proceeding characteristic, this parameter is related to the surface state, the homogeneity of the conductor and to the wiper design. It is expressed as a percent of the Total Applied Voltage. Operational performance better than the guaranteed value of $2.5^{\pm 0.025}$ % is obtained over the total electrical travel.

++ Low temperature perfonnance:

A noteworthy advantage of this technology is that the output smoothness is maintained at very low temperatures (– 55°C).

+ Temperature coefficient:

Depending upon the potentiometer value, the temperature coefficient is generally negative.

+ Performance versus frequency:

Parameters having an influence on the input and output impedances remain negligible due to the absence of a coil, for frequencies up to 100 kHz, whatever the potentiometer value and wiper position.

++ Life:

Conductive polymer potentiometers have a life superior to that of wirewound potentiometers, reaching 25.10^6 shaft revolutions at 400 rpm, as long as usage conditions are followed (output current value).